



ÇANKAYA UNIVERSITY
Department of Mathematics

MATH 255 - Vector Calculus and Linear Algebra

Final Exam

23.05.2018

SAMPLE SOLUTIONS

STUDENT NUMBER:

NAME-SURNAME:

SIGNATURE:

INSTRUCTOR: E.M.T.

DURATION: 100 minutes

Question	Grade	Out of
1		20
2		20
3		20
4		20
5		20
Total		100

IMPORTANT NOTES:

- 1) Please make sure that you have written your student number and name above.
- 2) Check that the exam paper contains 5 problems.
- 3) Show all your work. No points will be given to correct answers without reasonable work.

1. Let S be the part of the paraboloid $z = x^2 + y^2$ lying above the region $x^2 + y^2 = 2y$ with downward unit normal vector \vec{n} and C be the boundary curve of S oriented in the clockwise direction when viewed from above (note that orientation of C is positive with respect to \vec{n}). Use Stoke's Theorem to evaluate $\oint_C \vec{F} \cdot d\vec{r}$ where $\vec{F}(x, y, z) = (3y + z, x - z, x + 2y) = (3y + z)\vec{i} + (x - z)\vec{j} + (x + 2y)\vec{k}$.

$$\begin{aligned} x^2 + y^2 - 2y &= 0 \\ x^2 + (y-1)^2 &= 1^2 \\ r^2 - 2rsin\theta &= 0 \\ r=0 &\quad r=2sin\theta \end{aligned}$$

$D: 0 \leq \theta \leq \pi$
 $0 \leq r \leq 2\sin\theta$

S is smooth, orientable, C is smooth, closed, positively oriented boundary of S relative to the unit normal vector \vec{n} of S . $M = 3y + z$, $N = x - z$, $P = x + 2y$ are polynomials. Hence they have continuous first partial derivatives.

So by Stoke's theorem $\oint_C \vec{F} \cdot d\vec{r} = \iint_S (\vec{\nabla} \times \vec{F}) \cdot \vec{n} dS$

A parametrization of S is

$$A(r, \theta) = \langle r\cos\theta, r\sin\theta, r^2 \rangle, \quad (r, \theta) \in D$$

$$A_r = \langle \cos\theta, \sin\theta, 2r \rangle$$

$$A_\theta = \langle -r\sin\theta, r\cos\theta, 0 \rangle$$

$$\text{A normal vector to } S \text{ is } N = A_r \times A_\theta = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ \cos\theta & \sin\theta & 2r \\ -r\sin\theta & r\cos\theta & 0 \end{vmatrix}$$

$$= \langle -2r^2\cos\theta, -2r^2\sin\theta, r \rangle$$

$$\text{So } \vec{n} dS = -\frac{N}{\|N\|} \|N\| d\tau d\theta$$

$$= \langle 2r^2\cos\theta, 2r^2\sin\theta, -r \rangle d\tau d\theta$$

$$\vec{\nabla} \times \vec{F} = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ 3y+z & x-z & x+2y \end{vmatrix} = \langle 2 - (-1), -(1-1), 1 - 3 \rangle \\ = \langle 3, 0, -2 \rangle$$

$$\text{So } \oint_C \vec{F} \cdot d\vec{r} = \iint_S \vec{\nabla} \times \vec{F} \cdot \vec{n} dS = \int_0^\pi \int_0^{2\sin\theta} \langle 3, 0, -2 \rangle \cdot \langle 2r^2\cos\theta, 2r^2\sin\theta, -r \rangle dr d\theta$$

$$= \int_0^\pi \int_0^{2\sin\theta} (6r^2\cos\theta + 2r) dr d\theta = \int_0^\pi \left(2r^3\cos\theta \Big|_0^{2\sin\theta} + r^2 \Big|_0^{2\sin\theta} \right) d\theta$$

$$= \int_0^\pi (16\sin^3\theta\cos\theta + 4\sin^2\theta) d\theta$$

$$\frac{du = \sin\theta \cos\theta d\theta}{d\theta}$$

$$\int 16\sin^3\theta\cos\theta d\theta = \int 16u^3 du = 4u^4 + C = 4\sin^4\theta + C$$

$$\begin{aligned}&= 4 \sin^4 \theta \int_0^\pi + \int_0^\pi 2(1-\cos 2\theta) d\theta \\&= 4 \sin^4 \pi - 4 \sin^4 0 + (2\theta - \sin 2\theta) \Big|_0^\pi \\&= 2\pi - \sin 4\pi - 0 + \sin 0 \\&= 2\pi.\end{aligned}$$

2. This question has FOUR unrelated parts.

$$\text{Let } A = \begin{bmatrix} 1 & 1 & 1 & 0 & 0 & 5 \\ 1 & 2 & 0 & 0 & 0 & 7 \\ 1 & 1 & 1 & 1 & 1 & 6 \\ 1 & 1 & 1 & 0 & 1 & 2 \end{bmatrix}.$$

- (a) Find a basis for the null space of A (i.e. the solution space of the system $Ax = 0$).
- (b) Find a basis for the column space of A .
- (c) Find a basis for the row space of A .
- (d) Find the rank and nullity of A .

$$A \xrightarrow{-R_1+R_2} \xrightarrow{-R_1+R_3} \xrightarrow{-R_1+R_4} \begin{bmatrix} 1 & 1 & 1 & 0 & 0 & 5 \\ 0 & 1 & -1 & 0 & 0 & 2 \\ 0 & 0 & 0 & 1 & 1 & 1 \\ 0 & 0 & 0 & 0 & 1 & -3 \end{bmatrix} \xrightarrow{-R_2+R_1} \xrightarrow{-R_4+R_3} \begin{bmatrix} 1 & 0 & 2 & 0 & 0 & 3 \\ 0 & 1 & -1 & 0 & 0 & 2 \\ 0 & 0 & 0 & 1 & 0 & 4 \\ 0 & 0 & 0 & 0 & 1 & -3 \end{bmatrix}$$

$\uparrow \quad \uparrow \quad \uparrow \quad \uparrow$

a) $x + 2z + 3w = 0$ $x = -2z - 3w$
 $y - z + 2w = 0$ $y = z - 2w$
 $t + 4w = 0$ $t = -4w$
 $u - 3w = 0$ $u = 3w$

$$\begin{pmatrix} x \\ y \\ z \\ t \\ u \\ w \end{pmatrix} = \begin{pmatrix} -2z - 3w \\ z - 2w \\ z \\ -4w \\ 3w \\ w \end{pmatrix} = z \begin{pmatrix} -2 \\ 1 \\ 1 \\ -4 \\ 3 \\ 1 \end{pmatrix} + w \begin{pmatrix} -3 \\ -2 \\ 0 \\ -4 \\ 0 \\ 1 \end{pmatrix}$$

$$\left\{ \begin{pmatrix} -2 \\ 1 \\ 1 \\ -4 \\ 3 \\ 1 \end{pmatrix}, \begin{pmatrix} -3 \\ -2 \\ 0 \\ -4 \\ 0 \\ 1 \end{pmatrix} \right\}$$

$$\text{b) } \left\{ \begin{pmatrix} 1 \\ 1 \\ 1 \\ 1 \end{pmatrix}, \begin{pmatrix} 1 \\ 2 \\ 1 \\ 1 \end{pmatrix}, \begin{pmatrix} 0 \\ 0 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 0 \\ 0 \\ 1 \end{pmatrix} \right\}$$

$$\text{c) } \left\{ \begin{bmatrix} 1 & 0 & 2 & 0 & 0 & 3 \end{bmatrix}, \begin{bmatrix} 0 & 1 & -1 & 0 & 0 & 2 \end{bmatrix}, \begin{bmatrix} 0 & 0 & 0 & 1 & 0 & 4 \end{bmatrix}, \begin{bmatrix} 0 & 0 & 0 & 0 & 1 & -3 \end{bmatrix} \right\}$$

$$\text{d) } \text{rank}(A) = 4 \\ \text{nullity}(A) = 2.$$

3. Let $W = \left\{ \begin{bmatrix} a & b \\ 0 & c \end{bmatrix} \mid a, b, c \in \mathbb{R} \right\}$.

(a) Show that W is a subspace of $\mathbb{R}^{2 \times 2}$.

$0 \in \mathbb{R}$ so $\begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix} \in W$ Hence $W \neq \emptyset$.

Let $A, B \in W$, then there are $a, b, c, d, e, f \in \mathbb{R}$ s.t. $A = \begin{bmatrix} a & b \\ 0 & c \end{bmatrix}$ and $B = \begin{bmatrix} d & e \\ 0 & f \end{bmatrix}$.

$$A+B = \begin{bmatrix} a & b \\ 0 & c \end{bmatrix} + \begin{bmatrix} d & e \\ 0 & f \end{bmatrix} = \begin{bmatrix} a+d & b+e \\ 0 & c+f \end{bmatrix} \in W \text{ as } a+d, b+e, c+f \in \mathbb{R}.$$

Let $k \in \mathbb{R}$.

$$kA = \begin{bmatrix} ka & kb \\ 0 & kc \end{bmatrix} \in W \text{ as } ka, kb, kc \in \mathbb{R}.$$

Thus, W is a subspace of $\mathbb{R}^{2 \times 2}$.

(b) Find a basis S for W .

$$\begin{bmatrix} a & b \\ 0 & c \end{bmatrix} = a \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} + b \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix} + c \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix} = \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix} \rightarrow a=b=c=0$$

$S = \left\{ \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix} \right\}$ is a basis for W .

(c) Find a basis B for $\mathbb{R}^{2 \times 2}$ containing S .

The standard basis for $\mathbb{R}^{2 \times 2}$ is $\left\{ \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix} \right\}$

$$\left[\begin{array}{cccc} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{array} \right] \xrightarrow{R_3 \leftrightarrow R_4} \left[\begin{array}{cccc} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{array} \right]$$

$$\text{So } B = \left\{ \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix} \right\}$$

4. This question has TWO unrelated parts.

Let $\langle \cdot, \cdot \rangle : \mathbb{P}_2 \times \mathbb{P}_2 \rightarrow \mathbb{R}$ be defined by $\langle p(x), q(x) \rangle = \int_1^2 p(x)q(x)dx$
for $p(x), q(x) \in \mathbb{P}_2$.

(a) Show that $\langle \cdot, \cdot \rangle$ is an inner product on \mathbb{P}_2 .

(b) Find an orthonormal basis for the inner product space \mathbb{P}_2 with the inner product $\langle \cdot, \cdot \rangle$ defined above by applying the Gram-Schmidt Orhtogonalization Process to the standard basis $\beta = \{1, x, x^2\}$ of \mathbb{P}_2 .

a) Let $p(x), q(x), r(x) \in \mathbb{P}_2$, $a \in \mathbb{R}$.

$$\langle p(x), p(x) \rangle = \int_1^2 p(x)p(x)dx = \int_1^2 (p(x))^2 dx \geq 0 \text{ as } (p(x))^2 \geq 0.$$

for all $x \in [1, 2]$.

$$\langle p(x), p(x) \rangle = 0 \iff \int_1^2 (p(x))^2 dx = 0$$

As $1 \neq 2$ and $(p(x))^2 \geq 0$ we have $(p(x))^2 = 0$

which is the case $p(x) = 0$.

$$\langle q(x), p(x) \rangle = \int_1^2 q(x)p(x)dx = \int_1^2 p(x)q(x)dx = \langle p(x), q(x) \rangle.$$

$$\begin{aligned} \langle p(x) + q(x), r(x) \rangle &= \int_1^2 (p(x) + q(x))r(x)dx \\ &= \int_1^2 (p(x)r(x) + q(x)r(x))dx \\ &= \int_1^2 p(x)r(x)dx + \int_1^2 q(x)r(x)dx \\ &= \langle p(x), r(x) \rangle + \langle q(x), r(x) \rangle. \end{aligned}$$

$$\langle a p(x), q(x) \rangle = \int_1^2 a p(x)q(x)dx = a \int_1^2 p(x)q(x)dx = a \langle p(x), q(x) \rangle.$$

So $\langle \cdot, \cdot \rangle$ is an inner product on \mathbb{P}_2 .

b) $p_1(x) = 1$

$$\begin{aligned} p_2(x) &= x - \frac{\langle p_1(x), x \rangle}{\langle p_1(x), p_1(x) \rangle} p_1(x) \\ &= x - \frac{\frac{3}{2}}{1} \cdot 1 = x - \frac{3}{2}. \end{aligned}$$

$$\begin{aligned} \langle p_1(x), x \rangle &= \langle 1, x \rangle = \int_1^2 x dx \\ &= \frac{x^2}{2} \Big|_1^2 = \frac{4}{2} - \frac{1}{2} = \frac{3}{2} \\ \langle p_1(x), p_1(x) \rangle &= \langle 1, 1 \rangle = \int_1^2 1 dx = 2 - 1 = 1 \end{aligned}$$

$$p_3(x) = x^2 - \frac{\langle p_1(x), x^2 \rangle}{\langle p_1(x), p_1(x) \rangle} p_1(x) - \frac{\langle p_2(x), x^2 \rangle}{\langle p_2(x), p_2(x) \rangle} p_2(x)$$

$$\begin{aligned} \langle p_1(x), x^2 \rangle &= \langle 1, x^2 \rangle = \int_1^2 x^2 dx \\ &= \frac{x^3}{3} \Big|_1^2 = \frac{8}{3} - \frac{1}{3} = \frac{7}{3} \\ \langle p_2(x), x^2 \rangle &= \int_1^2 x^2 \cdot \frac{3}{2} dx = \frac{3}{2} \int_1^2 x^2 dx = \frac{3}{2} \cdot \frac{7}{3} = \frac{7}{2} \end{aligned}$$

$$P_3(x) = x^2 - \frac{7}{1} 1 - \frac{\frac{1}{4}}{\frac{1}{12}} (x - \frac{3}{2})$$

$$= x^2 - \frac{7}{3} - 3x + \frac{9}{2}$$

$$= x^2 - 3x + \frac{27 - 14}{6}$$

$$= x^2 - 3x + \frac{13}{6}$$

$$\langle P_3(x), P_3(x) \rangle = \int_1^2 \left(x^2 - 3x + \frac{13}{6} \right)^2 dx$$

$$= \int_1^2 \left(x^4 + 9x^2 + \frac{169}{36} - 6x^3 + \frac{13}{3}x^2 - 13x \right) dx$$

$$= \frac{x^5}{5} + 3x^3 + \frac{169}{36}x^2 - \frac{3}{2}x^4 + \frac{13}{9}x^3 - \frac{13}{2}x^2$$

$$= \frac{32}{5} + 24 + \frac{169}{18} - 24 + \frac{104}{9} - 26$$

$$- \frac{1}{5} - 3 - \frac{169}{36} + \frac{3}{2} - \frac{13}{9} + \frac{13}{2}$$

$$= \frac{31}{5} + \frac{169}{36} + \frac{91}{9} - 29 + 8$$

$$= \frac{1116 + 845 + 1820}{180} - 21$$

$$= \frac{3781 - 3780}{180} = \frac{1}{180}$$

$$q_1(x) = \frac{P_1(x)}{\sqrt{\langle P_1(x), P_1(x) \rangle}} = \frac{1}{1} = 1$$

$$q_2(x) = \frac{P_2(x)}{\sqrt{\langle P_2(x), P_2(x) \rangle}} = \frac{x - \frac{3}{2}}{\frac{1}{12}} = 12x - 18$$

$$q_3(x) = \frac{P_3(x)}{\sqrt{\langle P_3(x), P_3(x) \rangle}} = \frac{x^2 - 3x + \frac{13}{6}}{\frac{1}{180}} = 180x^2 - 540x + 390$$

$\{q_1, q_2, q_3\}$ is an orthonormal basis for P_2 .

$$\langle P_2(x), x^2 \rangle = \langle x - \frac{3}{2}, x^2 \rangle$$

$$= \int_1^2 (x - \frac{3}{2}) x^2 dx$$

$$= \int_1^2 (x^3 - \frac{3}{2}x^2) dx$$

$$= \left(\frac{x^4}{4} - \frac{x^3}{2} \right) \Big|_1^2$$

$$= \frac{16}{4} - \frac{8}{2} - \frac{1}{4} + \frac{1}{2}$$

$$= \frac{15}{4} - \frac{7}{2} = \frac{1}{4}$$

$$\langle P_2(x), P_2(x) \rangle = \langle x - \frac{3}{2}, x - \frac{3}{2} \rangle$$

$$= \int_1^2 (x^2 - 3x + \frac{9}{4}) dx$$

$$= \frac{x^3}{3} - \frac{3}{2}x^2 + \frac{9}{4}x \Big|_1^2$$

$$= \frac{8}{3} - \frac{3}{2} \cdot 4 + \frac{9}{4} \cdot 2 - \frac{1}{3} + \frac{3}{2} - \frac{9}{4}$$

$$= \frac{7}{3} - \frac{9}{2} + \frac{9}{4}$$

$$= \frac{7}{3} - \frac{9}{4} = \frac{28 - 27}{12} = \frac{1}{12}$$

5. Use Cramer's Rule to solve the system

$$\begin{aligned}x &+ 2y + 5z = 2 \\2x &- y + 3z = 7 \\-x &- y + 2z = 3\end{aligned}$$

$$A = \begin{bmatrix} 1 & 2 & 5 \\ 2 & -1 & 3 \\ -1 & -1 & 2 \end{bmatrix} \quad b = \begin{bmatrix} 2 \\ 7 \\ 3 \end{bmatrix} \quad x = \begin{bmatrix} x \\ y \\ z \end{bmatrix}$$

$$Ax = b.$$

$$|A| = \begin{vmatrix} 1 & 2 & 5 \\ 2 & -1 & 3 \\ -1 & -1 & 2 \end{vmatrix} \xrightarrow{\substack{R_1+R_2 \\ R_1+R_3}} \begin{vmatrix} 1 & 2 & 5 \\ 0 & -3 & -2 \\ 0 & 0 & 7 \end{vmatrix} = 1 \cdot (-1)^{1+1} \begin{vmatrix} -5 & -2 \\ 1 & 7 \end{vmatrix} \\ = -35 + 7 = -28 \neq 0$$

So Cramer's rule is applicable.

$$|A_1| = \begin{vmatrix} 2 & 2 & 5 \\ 7 & -1 & 3 \\ 3 & -1 & 2 \end{vmatrix} \xrightarrow{\substack{2R_2+R_3 \\ -R_2+R_3}} \begin{vmatrix} 16 & 0 & 11 \\ 2 & -1 & 3 \\ -4 & 0 & -1 \end{vmatrix} = (-1)(-1)^{2+2} \begin{vmatrix} 16 & 11 \\ -4 & -1 \end{vmatrix} \\ = -(-16 + 44) = -28$$

$$|A_2| = \begin{vmatrix} 1 & 2 & 5 \\ 2 & 7 & 3 \\ -1 & 3 & 2 \end{vmatrix} \xrightarrow{\substack{-2R_1+R_2 \\ R_1+R_3}} \begin{vmatrix} 1 & 2 & 5 \\ 0 & 3 & -2 \\ 0 & 5 & 7 \end{vmatrix} = 1 \cdot (-1)^{1+1} \begin{vmatrix} 3 & -2 \\ 5 & 7 \end{vmatrix} \\ = 21 + 35 = 56$$

$$|A_3| = \begin{vmatrix} 1 & 2 & 2 \\ 2 & -1 & 7 \\ -1 & -1 & 3 \end{vmatrix} \xrightarrow{\substack{-2R_1+R_2 \\ R_1+R_3}} \begin{vmatrix} 1 & 2 & 2 \\ 0 & -5 & 3 \\ 0 & 1 & 5 \end{vmatrix} = 1 \cdot (-1)^{1+1} \begin{vmatrix} -5 & 3 \\ 1 & 5 \end{vmatrix} \\ = -25 - 3 = -28$$

$$\text{So } x = \frac{|A_1|}{|A|} = \frac{-28}{-28} = 1$$

$$y = \frac{|A_2|}{|A|} = \frac{56}{-28} = -2$$

$$z = \frac{|A_3|}{|A|} = \frac{-28}{-28} = 1 \quad \text{Hence} \quad \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} 1 \\ -2 \\ 1 \end{pmatrix}.$$